

In situ measurements to infer SSH

- Inference through dynamical balance/simple models (e.g., inversion from drifter trajectories or Helmholtz decomposition of surface current transects)
- Bottom-mounted inverted echo sounders with pressure recorders (Watts et al.)
- Differential GPS (Bonnefond et al.)
- Hydrographic (temperature/salinity) measurements for dynamic height; includes measurements from ships, moorings, profiling floats, and gliders

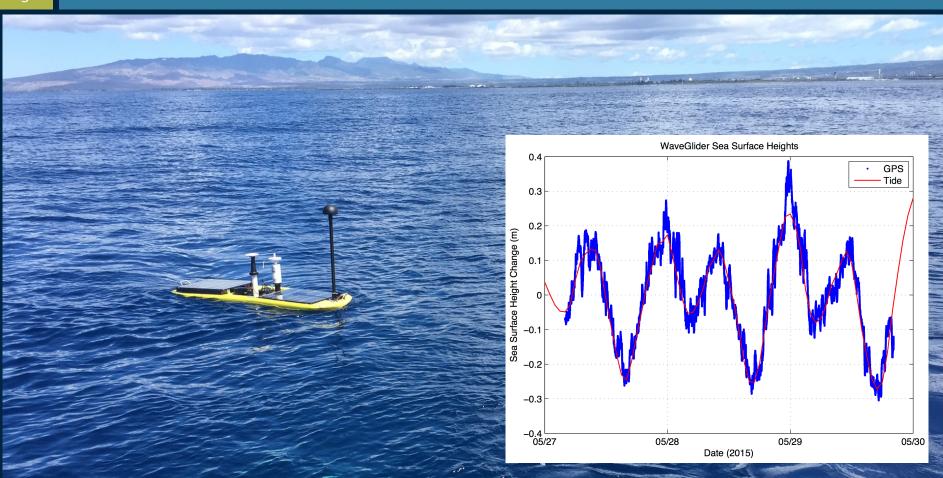
PIES (Pressure-recording Inverted Echo Sounder) Watts et al. talk following



- Emits 12 kHz sound pulses
- Measures τ = round-trip travel
 time from bottom to surface
- Measures bottom pressure (P_{bot}) – resolution < 1 mm
- A robust empirical relationship exists between τ and vertical profiles T(P), S(P)

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An array of autonomous mobile platforms, like wave gliders, might help capture synoptic SSH; needs to be evaluated (James Foster, Hawaii Inst of Geophys and Planetology; Dave Fratantoni, Seatrec)

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Hydrographic measurements for dynamic height



Hydrographic measurements for dynamic height

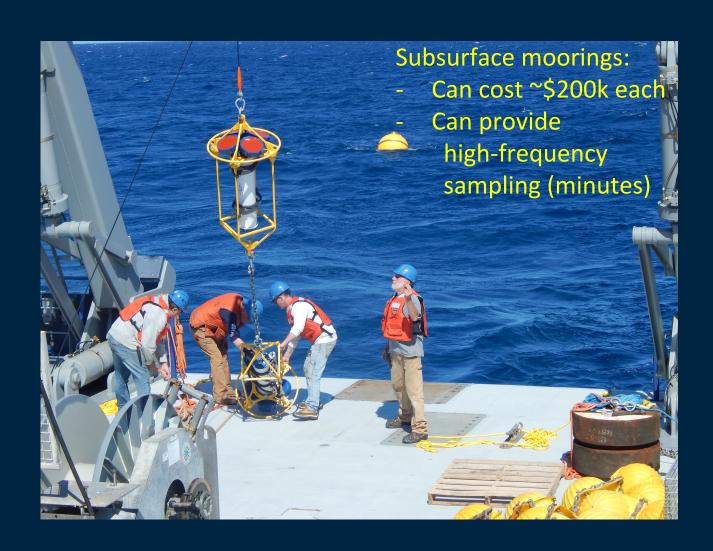
Shipboard hydrographic measurements involve an inherent trade-off of profile depth and ship speed. Table below is for a particular underway measurement system (OceanScience Underway CTD)



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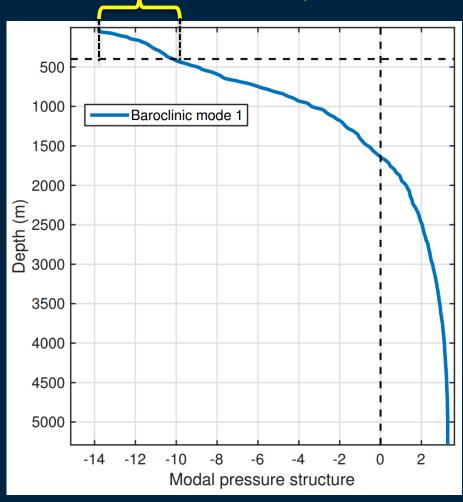
0 m

4700 m



Relationship of dynamic height to SSH

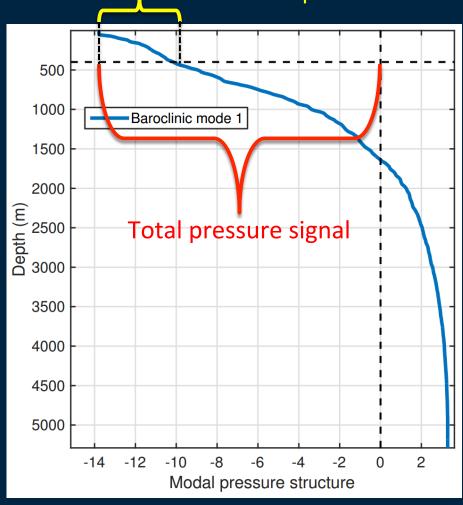
Pressure difference between surface and reference depth



← Reference depth

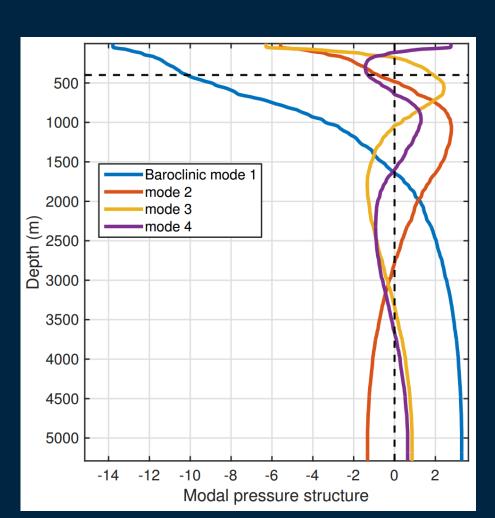
Relationship of dynamic height to SSH

Pressure difference between surface and reference depth



If we knew the vertical structure of the baroclinic pressure signal (and the barotropic pressure signal), it would be simple to relate dynamic height to SSH

Relationship of dynamic height to SSH



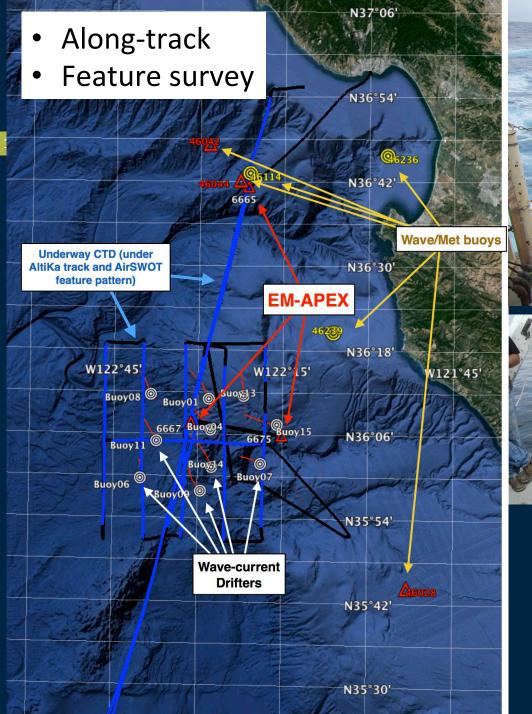
So, how can we relate dynamic height to SSH?

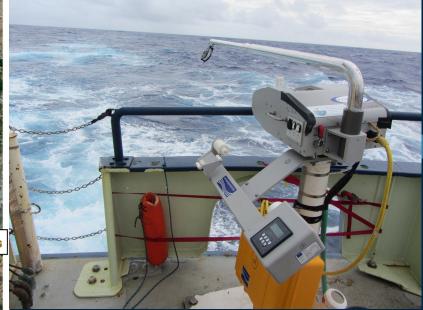
Two approaches:

- (1) Compute dynamic height relative to a known pressure (either measure bottom pressure or assume pressure fluctuation is zero at some depth)
- (2) Given knowledge of contribution of different modes to dynamic height, convert dynamic height signal of each mode to SSH

AirSWOT Ocean In Situ Sampling Objectives

- Provide SSH information (including both in situ and ancillary estimates) to help understand AirSWOT performance
- Provide surface velocity data to assess/correct the effect on AirSWOT measurements



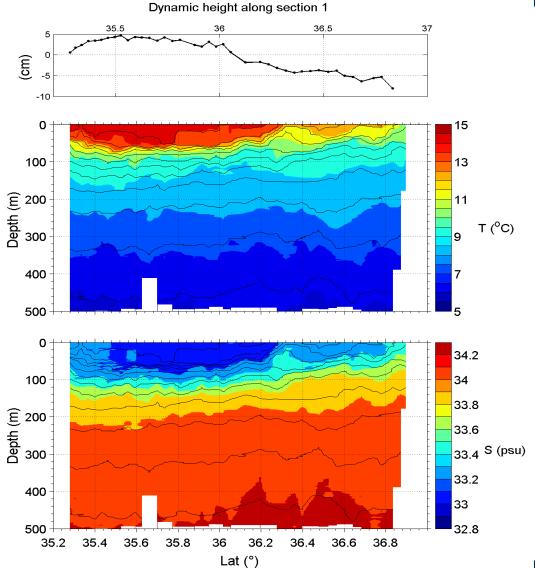






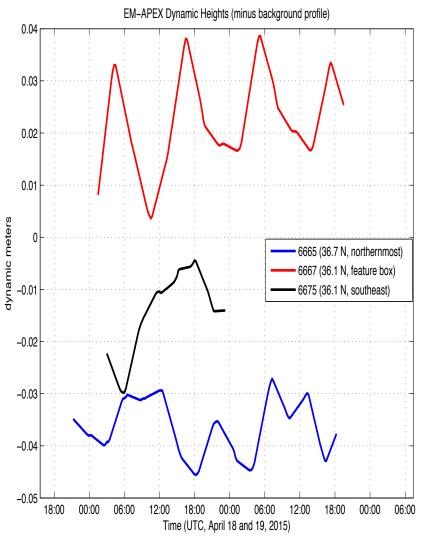
From Underway CTD:

• 10 cm SSH north-south gradient along-track

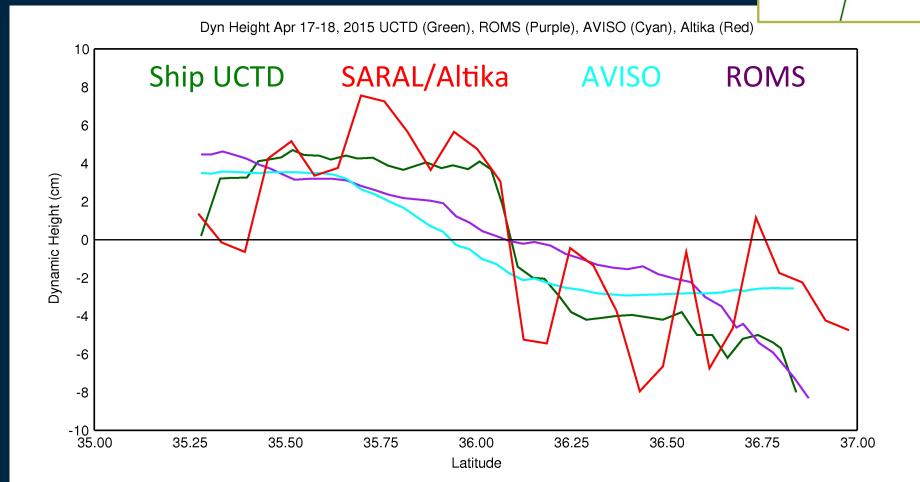


From James Girton's EM-APEX floats:

- 6 cm SSH north-south gradient
- 3 cm SSH due to internal tides/waves

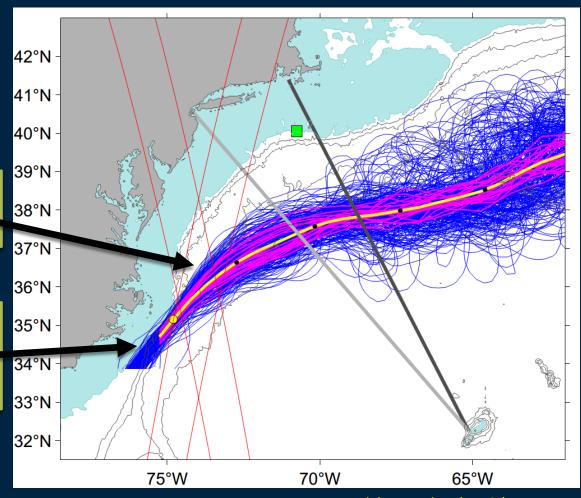


Along-track (SARAL/Altika) SSH on 17 April



SWOT fast-repeat orbit crossover

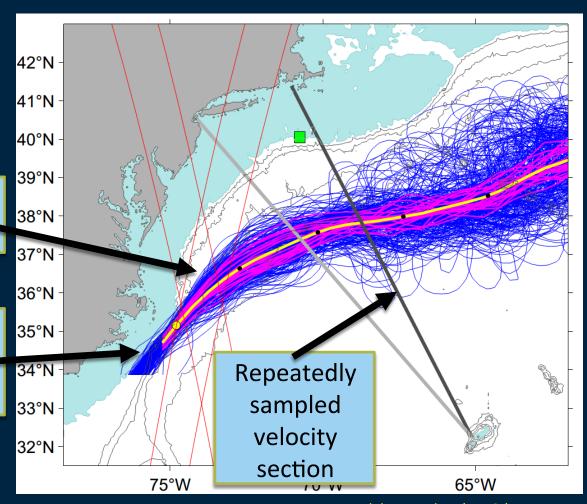
Gulf Stream center position from AVISO/
DUACS product



Magdalena Andres (WHOI)

SWOT fast-repeat orbit crossover

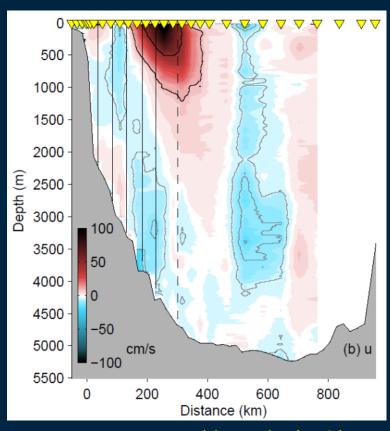
Gulf Stream center position from AVISO/
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1 m/s=86.4 km/day

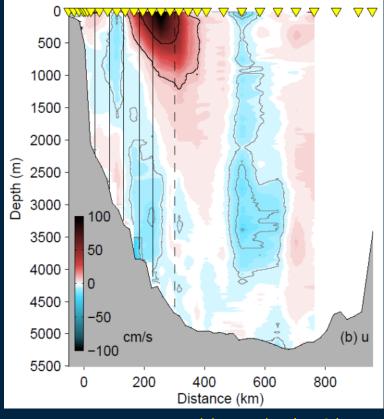
→ Major challenge for drifters, floats, gliders



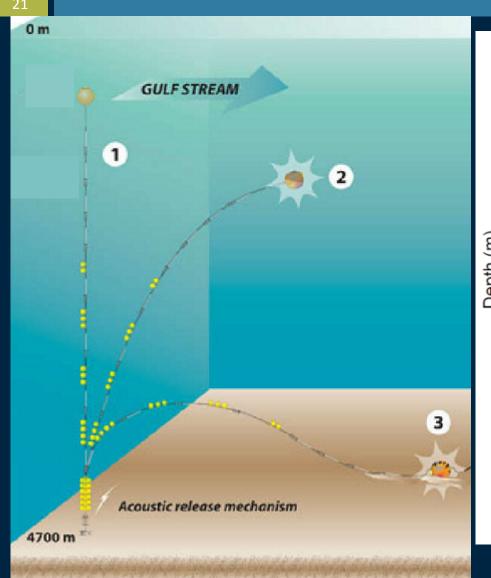
Magdalena Andres (WHOI)

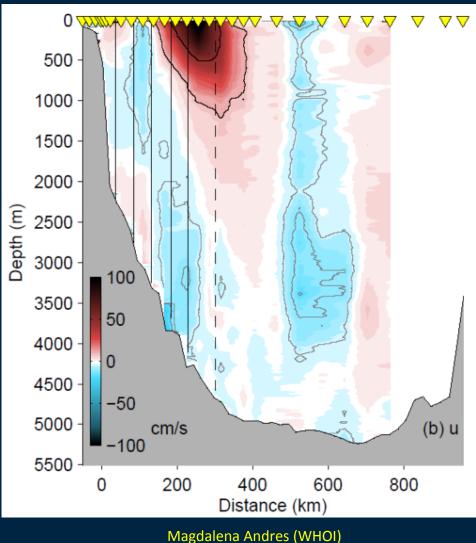
0 m

4700 m

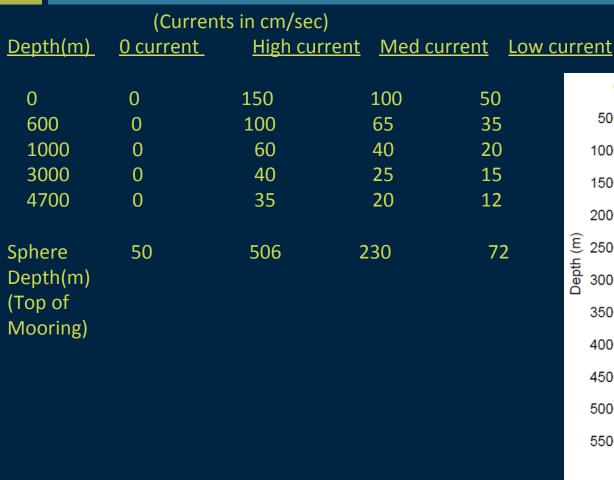


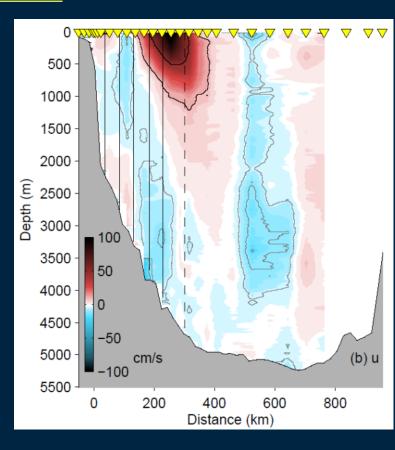
Magdalena Andres (WHOI)











Conclusions

- Hydrographic measurements provide an indirect measure of the baroclinic SSH signal
- There will be missing information from barotropic variability and unknown pressure at the reference depth—this can be a large "SSH" error
- Moorings can provide synoptic sampling, every few minutes for a year, but the number of sites would be limited

Vertical modes for April AirSWOT campaign

